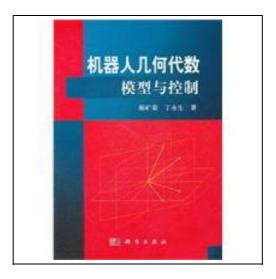# Algebraic geometry and control the robot model

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Reviews

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(Ms. Bernice Rolfson)

ALGEBRAIC GEOMETRY AND CONTROL THE ROBOT MODEL

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paperback. Condition: New. Ship out in 2 business day, And Fast shipping, Free Tracking number will be provided after the shipment.Pages Number: 352 Publisher: Science Press Pub. Date :2011-3-1. The book relies on the author's research. about the vector space. Lie algebra and the ring of even spinor theory and other mathematical tools in the machine the application of human kinematics. The book contains the basic theory of Lie algebra. kinematics. and body movement and control platform for visual inspection of three parts. The book is divided into 12 chapters. Chapter 1 Introduction; Chapter 2 the basic concepts of vector space reviewed; Section 3-5 for the Lie algebra and the ring of even the basic theory. introduced the Lie algebra of an even number. the dual Lie bracket and the inner product of the geometric meaning and relationships between them; Chapter 6-9 gives the ring of even spinor field in the kinematics of the application; Chapter 10-12 applications for the part of the book. gives the robot platform geometric invariant detection methods. and further combined with intelligent algorithms for visual servo control of robot dynamics are discussed. Although the book's approach to parallel muscle model based robots. but robots can also be used in series. and the spinor field in the ring of even the relevance of the research can be applied to the current configuration of the more popular integrated agency in. This book gives the analytical solution of the institutions learn new forms of expression. detection and control of robots for the follow-up basis. Finally. the book also gives intelligent detection and intelligent robot control method. Book as a graduate teaching or related professional undergraduate teaching. but also as related researchers and engineers reference book. Contents: Preface Introduction Chapter 1 describes the symbol 1.1 body geometry and algebraic...

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